## Why is $\sqrt[3]{-1} \neq -1$

Now that more people are getting better calculators they start to re-think what they always thought was obvious!

These new calculators give what we call the PRINCIPAL ROOT or PRIMARY ROOT.

It may sound a bit pedantic but  $\sqrt{9} = 3$  but not -3

However if we solve  $x^2 = 9$  we must write  $x = \pm \sqrt{9} = \pm 3$ We need the  $\pm$  sign because the root sign  $\sqrt{}$  only means the positive answer.

In fact  $\sqrt[3]{8}$  only means the principal root which is 2. but we do know there are 3 roots of  $x^3 = 8$ 

I like the simple De Moivre method...

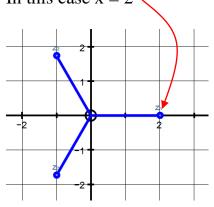
$$x^{3} = 8$$
  
 $[rcis(\theta)]^{3} = 8cis(0 + 360n)$   
 $r^{3}cis(3\theta) = 8cis(0 + 360n)$ 

$$r^3 = 8 \ so \ r = 2 \ and \ 3\theta = 360n \ so \ \theta = 120n = 0, 120, 240$$

The 3 solutions are:

$$x_1 = 2cis(\mathbf{0}) = 2cos(\mathbf{0}) + 2isin(\mathbf{0}) = 2$$
  
 $x_2 = 2cis(120) = 2cos(120) + 2isin(120) = -1 + i\sqrt{3}$   
 $x_3 = 2cis(240) = 2cos(240) + 2isin(240) = -1 - i\sqrt{3}$ 

The principal root is the first one found by De Moivre's Theorem. In this case x = 2



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However, if ...

$$x^{3} = -8$$

$$[rcis(\theta)]^{3} = 8cis(180 + 360n)$$

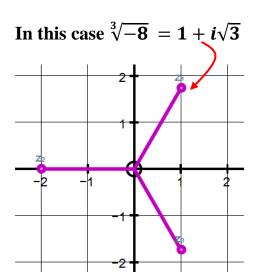
$$r^{3}cis(3\theta) = 8cis(180 + 360n)$$

$$r^3 = 8 \text{ so } r = 2 \text{ and } 3\theta = 60 + 360n \text{ so } \theta = 60, 180, 300$$

The 3 solutions are:

$$x_1 = 2cis(60) = 2cos(60) + 2isin(60) = 1 + i\sqrt{3}$$
  
 $x_2 = 2cis(180) = 2cos(180) + 2isin(180) = -2$   
 $x_3 = 2cis(300) = 2cos(300) + 2isin(300) = 1 - i\sqrt{3}$ 

The **principal root** is the first one found by De Moivre's Theorem.



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A good case is when NONE of the answers is real!

$$x^4 = -1$$
  
 $[rcis(\theta)]^4 = 1cis(180 + 360n)$   
 $r^4cis(4\theta) = 1cis(180 + 360n)$ 

$$r^4 = 1$$
 so  $r = 1$  and  $4\theta = 180 + 360n$  so  $\theta = 45, 135, 225, 315$ 

The 4 solutions are:

$$x_{1} = 1cis(45) = 1cos(45) + 1isin(45) = \frac{\sqrt{2}}{2} + i\frac{\sqrt{2}}{2}$$

$$x_{2} = 1cis(135) = 1\cos(135) + 1isin(135) = -\frac{\sqrt{2}}{2} + i\frac{\sqrt{2}}{2}$$

$$x_{3} = 1cis(225) = 1\cos(225) + 1isin(225) = -\frac{\sqrt{2}}{2} - i\frac{\sqrt{2}}{2}$$

$$x_{4} = 1cis(315) = 1\cos(315) + 1isin(315) = \frac{\sqrt{2}}{2} - i\frac{\sqrt{2}}{2}$$

